CHAPTER 7 HYDRAULIC ACTUATORS



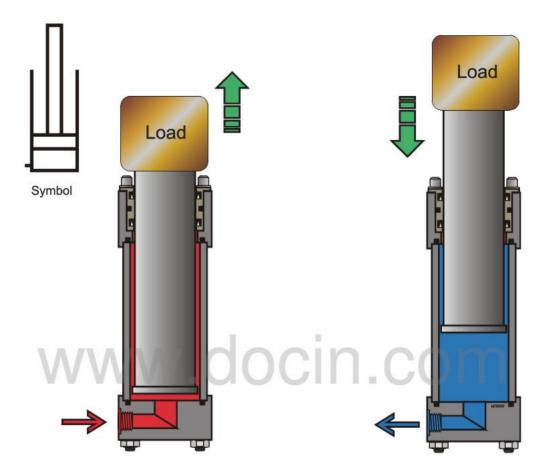


Figure 7-1 Ram Cylinder

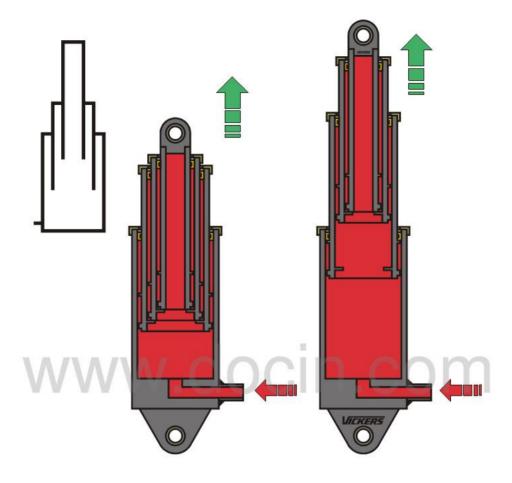


Figure 7-2 Single acting telescope cylinder

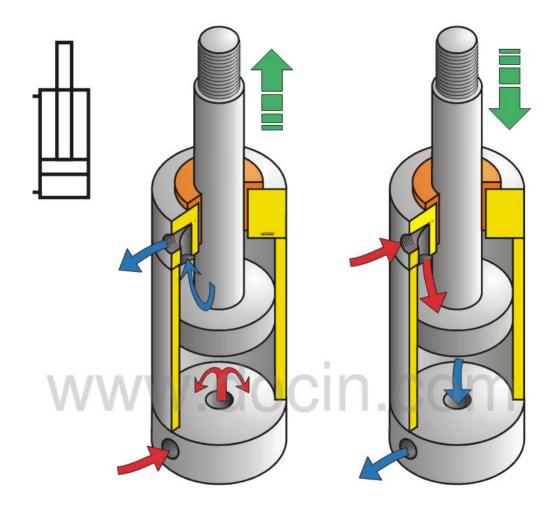


Figure 7-3 Basic double acting cylinder

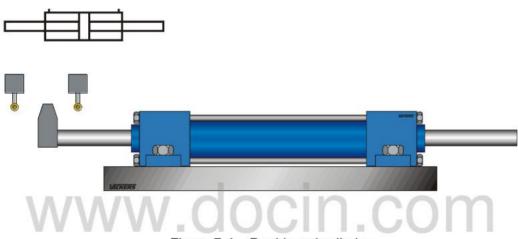


Figure 7-4 Double rod cylinder



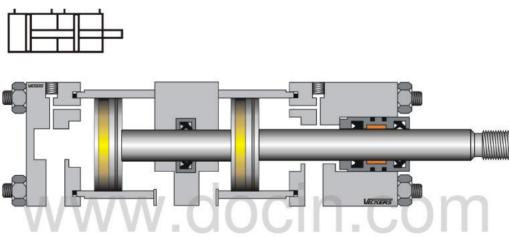


Figure 7-5 Tandem cylinder



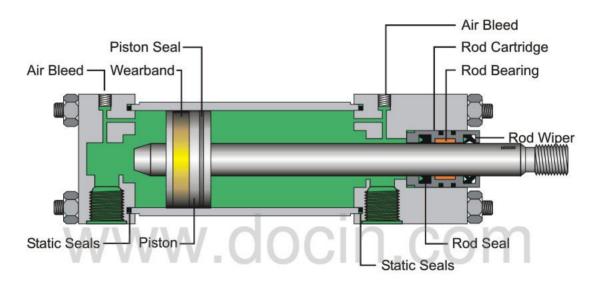


Figure 7-6 Typical cylinder construction



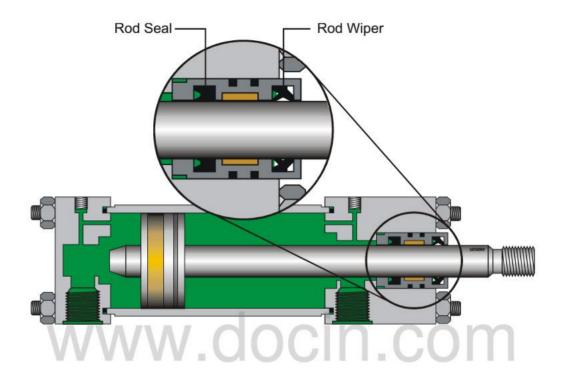


Figure 7-7 Rod seal and wiper design

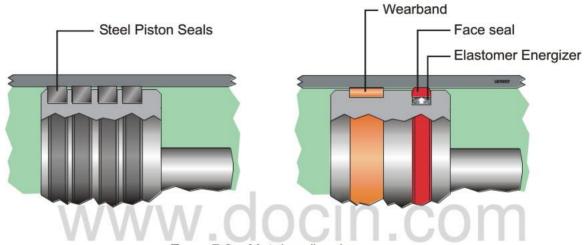


Figure 7-8 Metal sealing rings



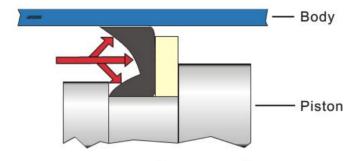


Figure 7-9 Pressure tightens the seal to improve sealing



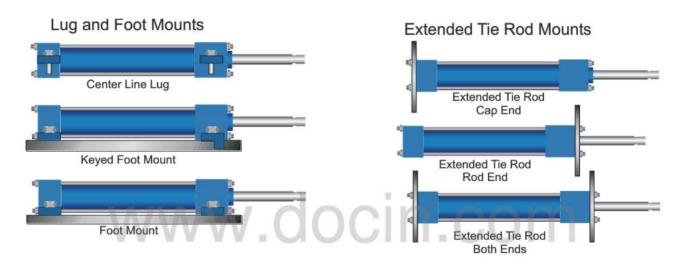


Figure 7-10 Cylinder mounting methods COPYRIGHT © (2001) EATON CORPORATION





Figure 7-10 Cylinder mounting methods COPYRIGHT (C) (2001) EATON CORPORATION



Trunnion Mounts

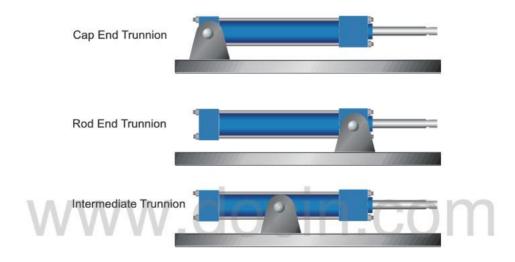


Figure 7-10 Cylinder mounting methods COPYRIGHT © (2001) EATON CORPORATION



Change	Speed	Load Pressure	Max Force
Increase relief valve setting	No effect	No effect No effect	
Decrease relief valve setting	No effect	No effect	Decrease
Increase gpm	Increase	No effect	No effect
Decrease gpm	Decrease	No effect	No effect
Increase cylinder diameter	Decrease	Decrease	Increase
Decrease cylinder diameter	Increase	Increase	Decrease

Table 7-1 Summary of effects of application changes on cylinder performance COPYRIGHT © (2001) EATON CORPORATION



Cyl. Bore Dia. Inch	Piston Rod Dia. Inch	Work Area Square Inch	Hydraulic Working Pressure PSI					Fluid Required per In of Stroke		Port Size	Fluid Velocity @ 15 ft/sec		
			500	750	1000	1500	2000	3000	Gal.	Cubic Inch	Dia Inch	Flow gpm	Piston Velocity in/sec
1-	5/8 1	1.767 1.460 .982	883 730 491	1325 1095 736	1767 1460 982	2651 2190 1473	3534 2920 1964	5301 4380 2946	.00765 .00632 .00425	1.767 1.460 .982	1/2	11.0	24.0 29.0 43.1
2	1 1 3/8	3.141 2.356 1.656	1571 1178 828	2356 1767 1242	3141 2356 1656	4711 3534 2484	6283 4712 3312	9423 7068 4968	.01360 .01020 .00717	3.141 2.356 1.656	1/2	11.0	13.5 18.0 25.6
2-	1 1 3/8 1	4.909 4.124 3.424 2.504	2454 2062 1712 1252	3682 3093 2568 1878	4909 4124 3424 2504	7363 6186 5136 3756	9818 8248 6848 5008	14727 12372 10272 7512	.02125 .01785 .01482 .01084	4.909 4.124 3.424 2.504	1/2	11.0	8.6 10.3 12.4 16.9
3-	1 3/8 1 2	8.296 6.811 5.891 5.154	4148 3405 2945 2577	6222 5108 4418 3865	8296 6811 5891 5154	12444 10216 8836 7731	16592 13622 11782 10308	24888 20433 17673 15462	.0359 .0295 .0255 .0223	8.296 6.811 5.891 5.154	3/4	20.3	9.4 11.5 13.3 15.2
4	1 2 2	12.566 10.161 9.424 7.657	6283 5080 4712 3828	9425 7621 7068 5743	12566 10161 9424 7657	18849 15241 14136 11485	25132 20322 18848 15314	37698 30483 28272 229781	.0544 .0440 .0408 .0331	12.566 10.161 9.424 7.657	3/4	20.3	6.2 7.7 8.3 10.2

Table 7-2 Data for various size cylinders COPYRIGHT © (2001) EATON CORPORATION



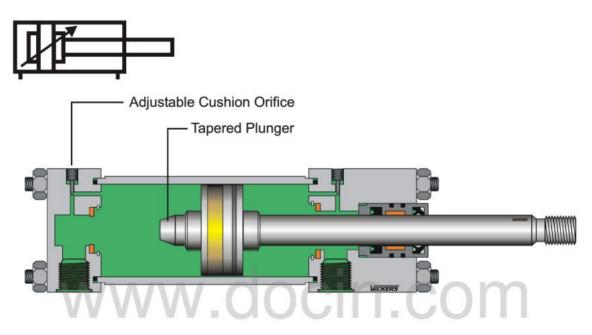


Figure 7-11 Cylinder with extension and retraction cushions



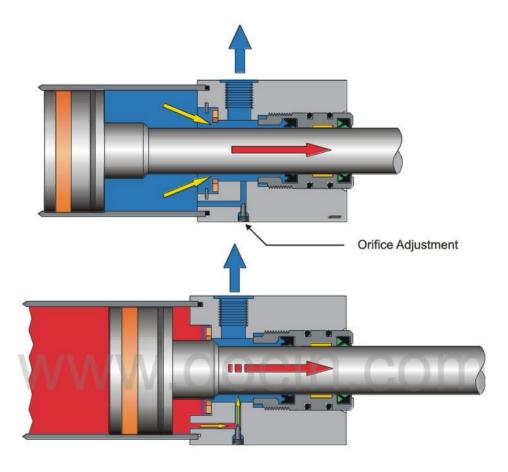


Figure 7-12 Rod end cushion during cylinder extension



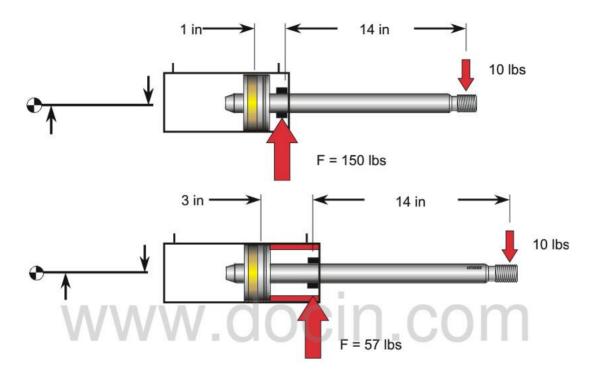


Figure 7-13 A stop tube provides better cylinder rod support

Center Support Tie Rod Spacer



Figure 7-14 Tie rod spacer and center support



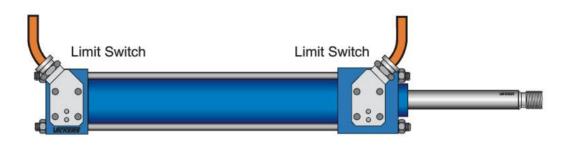


Figure 7-15 Cylinder with limit switches



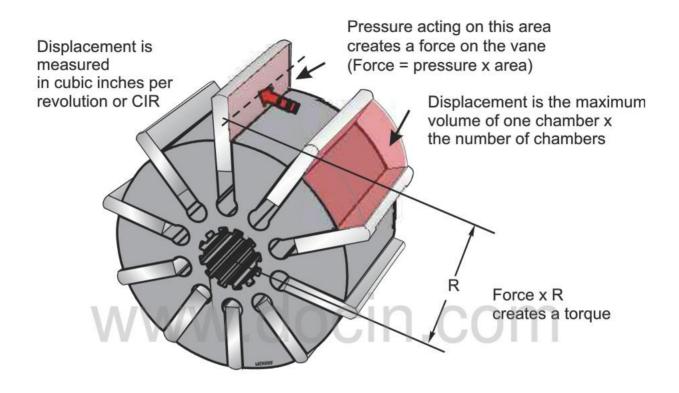


Figure 7-16 Displacement is the quantity of fluid that effects one shaft revolution

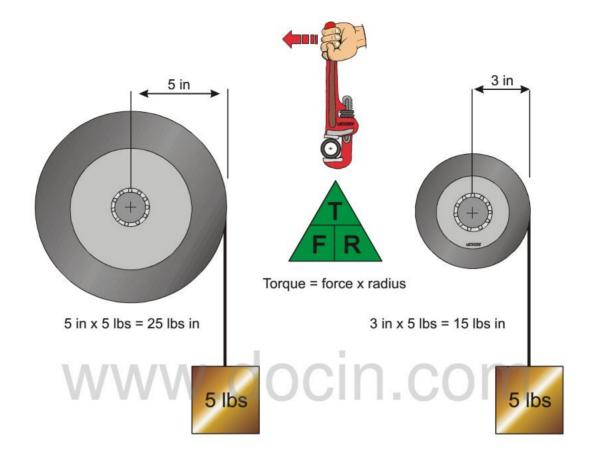


Figure 7-17 Torque equals load multiplied by radius

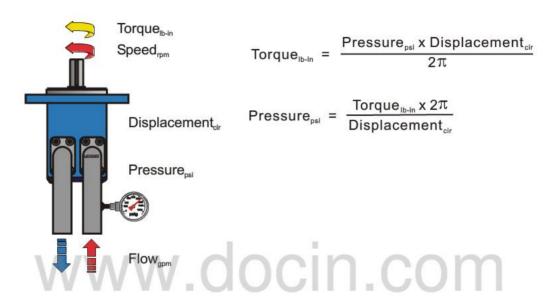


Figure 7-18 Hydraulic motor torque formula



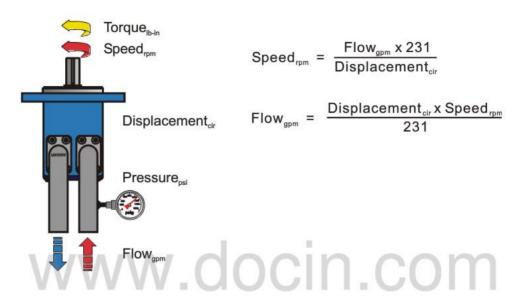


Figure 7-19 Hydraulic motor speed formula



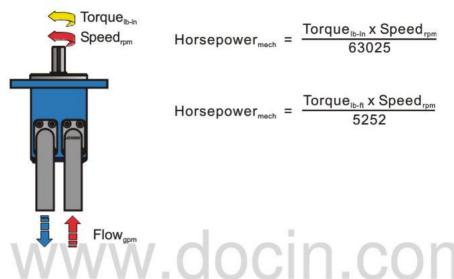


Figure 7-20 Hydraulic motor horsepower formula



Change	Speed	Load Pressure	Max Torque
Increase relief valve setting	No effect	No effect	Increase
Decrease relief valve setting	No effect	No effect	Decrease
Increase gpm	Increase	No effect	No effect
Decrease gpm	Decrease	No effect	No effect
Increase displacement cir	Decrease	Decrease	Increase
Decrease displacement cir	Increase	Increase	Decrease

Table 7-3 Summary of effects of application changes on motor operations COPYRIGHT © (2001) EATON CORPORATION



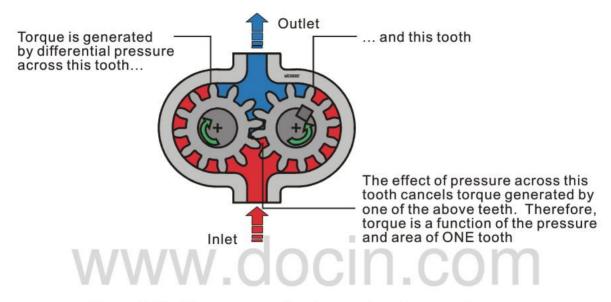


Figure 7-21 Torque generation in an external gear motor

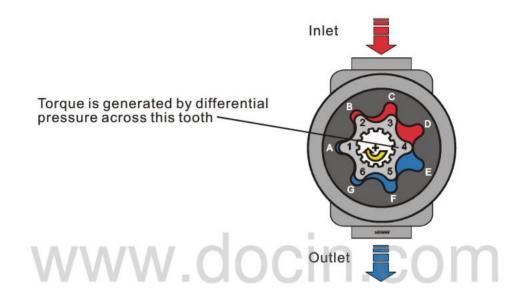


Figure 7-22 Cross section of a direct drive gerotor motor



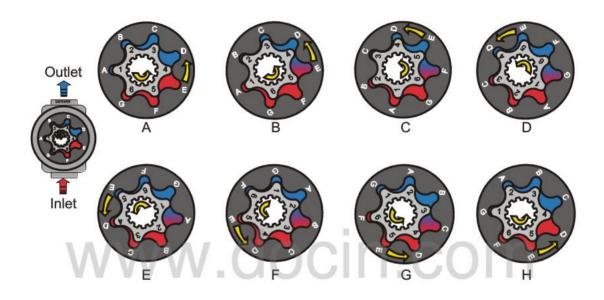


Figure 7-23 Sequence of direct drive gerotor motor

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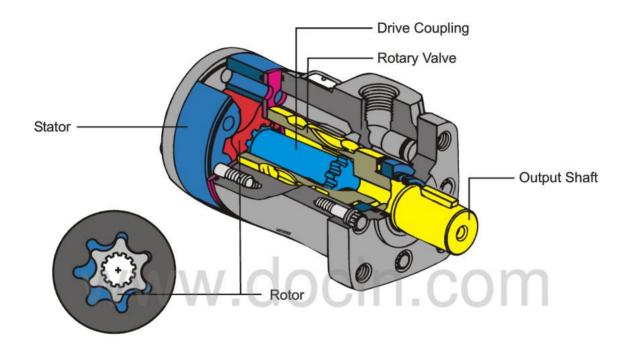


Figure 7-24 An orbiting gerotor motor



Figure 7-25 Sequence of an orbiting gerotor motor

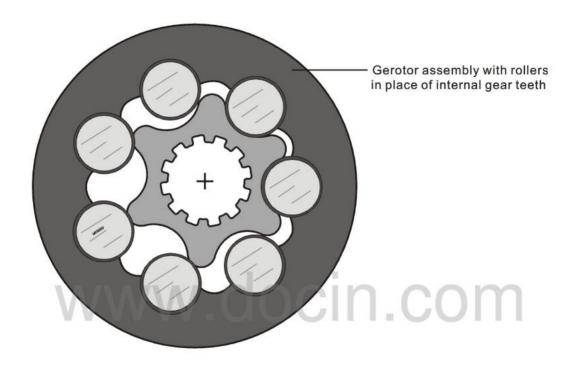


Figure 7.26 Roller-vane gerotor motor

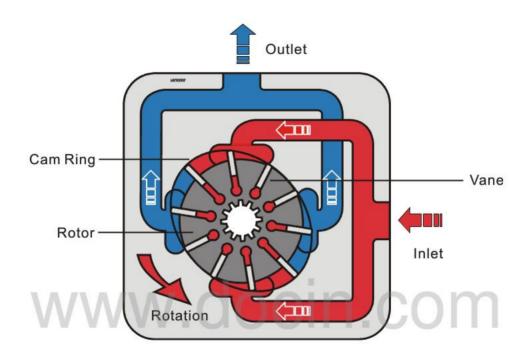


Figure 7-27 Cross section of a balanced vane motor rotating group

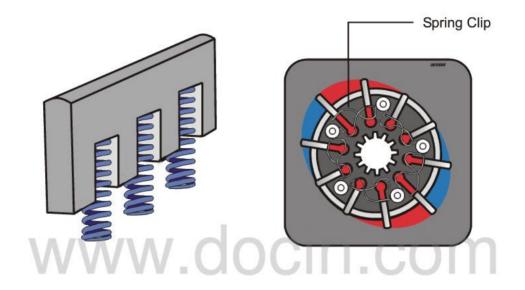


Figure 7-28 Springs or spring clips keep the vanes against the cam

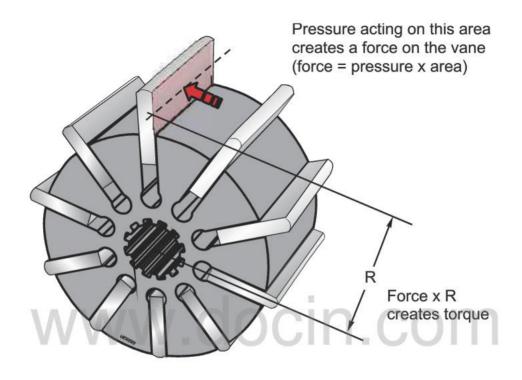


Figure 7-29 Pressure acting on a vane creates torque on the drive shaft COPYRIGHT © (2001) EATON CORPORATION

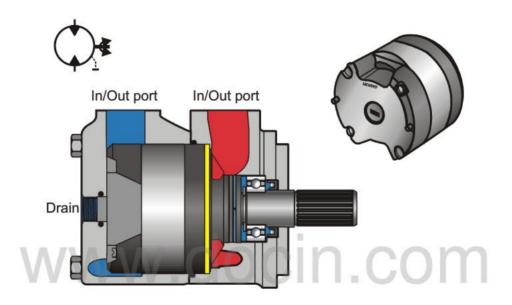


Figure 7-30 High performance vane motor cartridge design

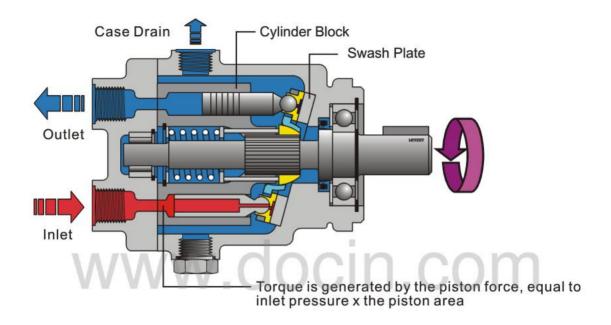


Figure 7-31 Fixed displacement in-line piston motor

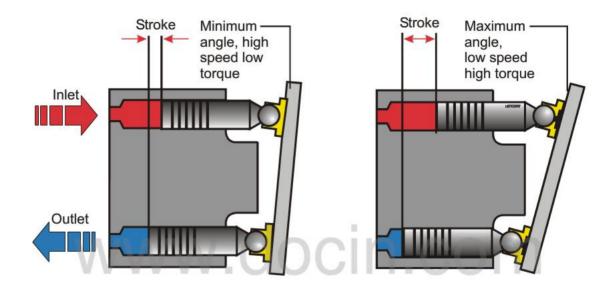


Figure 7-32 Swash plate angle determines the torque and speed relationship



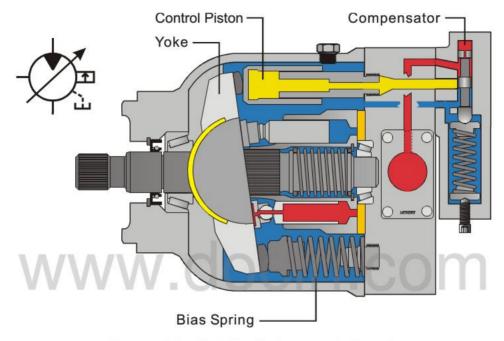


Figure 7-33 Variable displacement in-line piston motor

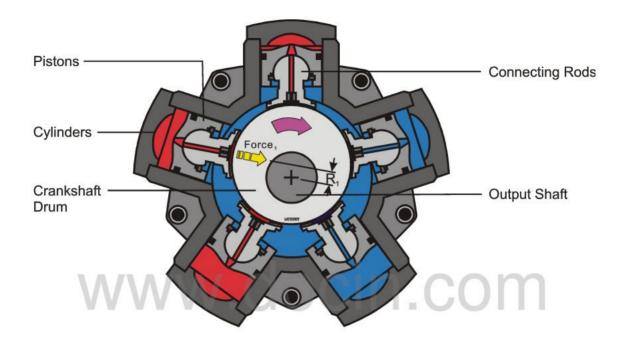


Figure 7-34 Radial piston motor

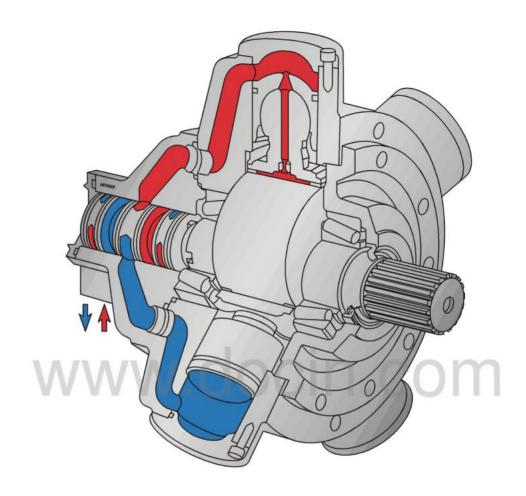


Figure 7-35 Inlet and outlet porting in a radial piston motor

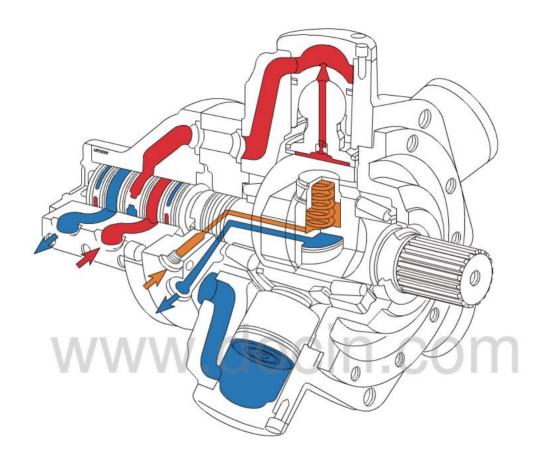


Figure 7-36 Variable displacement radial piston motor

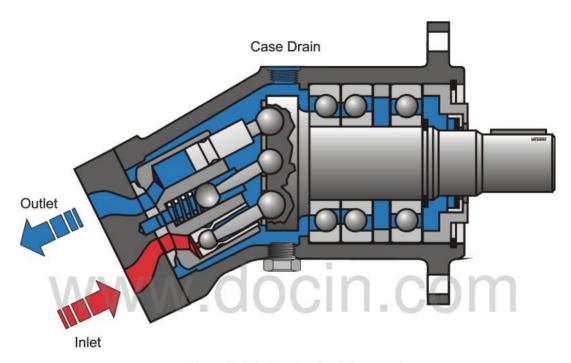


Figure 7-37 Bent axis piston motor

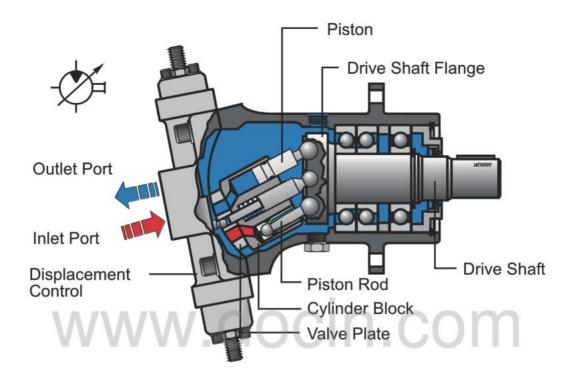


Figure 7-38 Variable displacement bent axis piston motor



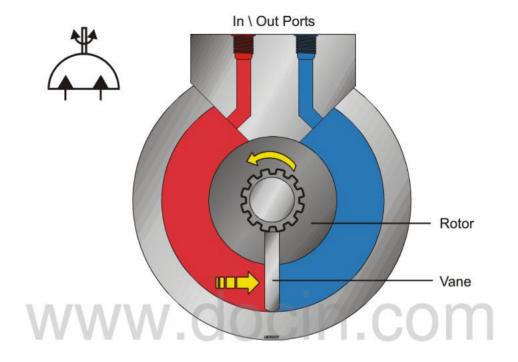


Figure 7-39 Limited rotation actuator

